



TAROS'23 & JOINT ROBOTICS CDT CONFERENCE



DAY 0: TUESDAY, 12 SEPTEMBER 2023

17:00
20:00

Student Registration & Welcome
Courtyard Marquee/Department of Engineering

DAY 1: WEDNESDAY, 13 SEPTEMBER 2023

08:00 – 09:00 **Registration (Day 1)**
Courtyard Marquee & LT4/Department of Engineering

DAY 1 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:15 **Welcome and Introduction**
Fumiya Iida

09:15 – 10:00 **Fernando Rodriguez y Baena**
Imperial College London

10:00 – 11:00 **Short Talks: Session 1**
Chair: Perla Maiolino

11:00 – 11:30 **BREAK: Refreshments**
Courtyard Marquee/Department of Engineering

11:30 – 12:30 **Short Talks: Session 2**
Chair: Mingfeng Wang

12:30 – 14:00 **LUNCH & Poster Sessions**
Courtyard Marquee & LT4/ LT1 & 2

14:00 – 14:45 **Jamie Shotton**
Wayve

14:45 – 15:45 **Short Talks: Session 3**
Chair: Arsen Abdulali

15:45 – 17:15 **Poster Sessions & Refreshments**
Courtyard Marquee/ LT1 & 2

18:30 – 19:00 **Reception & TAROS'23 Celebration Dinner**
at Robinson College

19:00 – 21:00

DAY 2: THURSDAY, 14 SEPTEMBER 2023

08:30 – 09:00 **Registration (Day 2)**
Courtyard Marquee & LT4/Department of Engineering

DAY 2 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:45 **Amanda Prorok**
University of Cambridge

09:45 – 10:45 **Short Talks: Session 1**
Chair:

10:45 – 11:15 **Coffee Break & Poster Session**
Courtyard Marquee/ LT1 & 2

11:15 – 12:15 **Short Talks: Session 2**
Chair:

12:15 – 14:00 **LUNCH & Poster Session**
Courtyard Marquee & LT4/ LT1 & 2
/Agriforwards CDT Steering Committee Meeting/

14:00 – 14:45 **Gert Kootstra**
Wageningen University
Chair: Prof Marc Hanheide

14:45 – 15:45 **Industry/Government/UK-RAS Forum**
Chair: Manuel Giuliani

15:45 – 16:30 **Coffee Break & Poster Session**
Courtyard Marquee/ LT1 & 2

16:30 – 17:00 **QMUL UK PhD Awards**
Chair: Lorenzo Jamone

17:00 – 17:30 **TAROS Awards**
Chair: Perla Maiolino

17:30 – 19:00 **Women in Robotics**
Chair: Isabelle Ormerod
LT1 & 2

19:30 – 21:00 **Academics & Industry Networking (Corpus Christi)**
Cambridge Pub Tour (Student activity)

DAY 3: FRIDAY, 15 SEPTEMBER 2023

08:30 – 09:00 **Registration (Day 3)**
Courtyard Marquee & LT4/Department of Engineering

DAY 3 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:30 **CDT Sessions INTRO**
Chairs: Fumiya Iida/Marc Hanheide

09:30 – 10:30 **CDT Session 1: CDT-RAS (Edinburgh)**
Chair: Marc Hanheide

10:30 – 11:00 **BREAK: Refreshments & all CDT Poster Session**
Courtyard Marquee/ LT1 & 2

11:00 – 12:00 **CDT Session 2: Farscope (Bristol)**
Chair: Helen McGloin

12:00 – 12:30 **CDT Panel: Student Training & Career**
Chair:

12:30 – 13:30 **LUNCH & Poster Session**
Courtyard Marquee & LT4/ Inglis Building Corridor & OHMC

13:30 – 14:30 **CDT Session 3: AIMS (Oxford)**

14:30 – 15:00 **CDT Panel: Future Collaborations**
Chair:

15:00 – 17:00 **Farewell Reception & Poster Session**
All AF CDT Students/Robotic Demonstrations
Courtyard Marquee/ Inglis Building Corridor & OHMC



DAY 0: TUESDAY, 12 SEPTEMBER 2023

17:00
20:00

Student Registration & Welcome

Courtyard Marquee/Department of Engineering



On Tuesday, the 12th of September 2023 we would like to invite all students attending the conference to an informal evening event that will include conference registration and a spread of pizza.



This is a low-key welcome gathering where students can meet and greet each other in the friendly surroundings of the courtyard behind the main building of the Department of Engineering that is on Trumpington Street.

Please come to pick up your conference name badge and a slice of pizza.



WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

08:00 – 09:00

Registration (Day 1)

Courtyard Marquee & LT4/Department of Engineering

DAY 1 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:15

Welcome and Introduction

Fumiya Iida

09:15 – 10:00

Fernando Rodriguez y Baena

Imperial College London

10:00 – 11:00

Short Talks: Session 1

Chair: Perla Mailino

11:00 – 11:30

BREAK: Refreshments

Courtyard Marquee/Department of Engineering

11:30 – 13:00

Short Talks: Session 2

Chair: Mingfeng Wang

13:00 – 14:00

LUNCH & Poster Sessions

Courtyard Marquee & LT4 / LT1 & 2/OHMC

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Jamie Shotton

Wayve

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Poster Sessions & Refreshments

Courtyard Marquee/LT1 & 2/OHMC

18:30 – 19:00

Reception & TAROS'23 Celebration Dinner at Robinson College

19:00 – 21:00

Prof Fernando Rodriguez y Baena

Imperial College London



Dr Jamie Shotton

Wayve





WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 1: WEDNESDAY, 13 SEPTEMBER 2023

08:00 – 09:00 **Registration (Day 1)**
Courtyard Marquee & LT4/
Department of Engineering

DAY 1 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:15 **Welcome and Introduction**
Fumiya Iida

09:15 – 10:00 **Keynote 1: Sethu Vijayakumar**
University of Edinburgh

10:00 – 11:00 **SHORT TALKS:
Locomotion & Manipulation**
Chair: Perla Maiolino

11:00 – 11:30 **BREAK: Refreshments**
Courtyard Marquee/Department of Engineering

11:30 – 13:00 **SHORT TALKS:
Visual & Tactile Sensing**
Chair: Mingfeng Wang

13:00 – 14:00 **LUNCH & Poster Sessions**
Courtyard Marquee & LT4 / LT1 & 2/OHMC

14:00 – 14:45 **Keynote 2: Jamie Shotton**
Wayve

14:45 – 15:45 **SHORT TALKS:
Machine Vision**
Chair: Arsen Abdulali

15:45 – 17:15 **Poster Sessions & Refreshments**
Courtyard Marquee/ LT1 & 2

18:30 – 19:00 **Reception & TAROS'23 Celebration Dinner**
at ROBINSON COLLEGE

19:00 – 21:00

	PRESENTER	PRESENTATION
SHORT TALKS: LOCOMOTION & MANIPULATION	Yunlong LIAN	<i>Cpg-based Locomotion Control Of A Quadruped Robot With An Active Spine</i>
	Catalin Stefan TEODORESCU	<i>Towards Wait-and-catch Routine Of A Dynamic Swinging Object Using A Prototype Robotic Arm Manipulator</i>
	Josh DAVY	<i>Simultaneous Base And Arm Trajectories For Multi-target Mobile Agri-robot</i>
	Wenxing LIU	<i>Sim-to-real Deep Reinforcement Learning With Manipulators For Pick-and-place</i>
CHAIR: PERLA MAIOLINO		

	PRESENTER	PRESENTATION
SHORT TALKS: VISUAL & TACTILE SENSING	Prasad RAYAMANE	<i>Human-Robot Handover with Vision-Based Tactile Sensors</i>
	N'Zebo Richard ANVO	<i>Automated 3D Mapping, localization and pavement inspection with low cost RGB-D cameras and IMUs</i>
	Gabriele GIUDICI	<i>Validation Of Multi-finger Robotic Telemanipulation System With Tactile Feedback</i>
	Jaskaran Singh WALIA	<i>Optimised Custom Dataset For Efficient Detection Of Underwater Trash</i>
CHAIR: MINGFENG WANG		

	PRESENTER	PRESENTATION
SHORT TALKS: MACHINE VISION	Sandeep BABU Majid JEGARIAN	<i>Fast 3D Semantic Segmentation Using a Self Attention Network and Random Sampling</i>
	Bradley HURST	<i>An assessment of self-supervised learning for data efficient potato instance segmentation</i>
	Charalampos MATSANTONIS	<i>A Geometric Algebra Solution to the 3D Registration Problem</i>
	Dario MANTEGAZZA	<i>Active Anomaly Detection for Autonomous Robots: a Benchmark</i>
CHAIR: ARSEN ABDULALI		



EPSRC Centre for Doctoral Training in Agri-Food Robotics



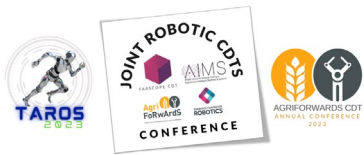
WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 1: WEDNESDAY, 13 SEPTEMBER 2023

POSTER SESSION 1

LECTURE THEATRE 1 (LT1)

PRESENTER	POSTER
David BATTY	<i>Occupancy Map Abstraction for Autonomous Ground Rover Exploration in Hazardous Environments</i>
Xiaoliang ZHANG	<i>Towards Long-horizon Motion Planning in Dynamic Environments</i>
Alex ELLERY	<i>What is a Universal Constructor that we should be Mindful of it?</i>
Daniel S. JOHNSON	<i>Receding Horizon Contact Planning for Advanced Motions in Hexapod Robots</i>
Roe M. FRANCOS	<i>Spiral Sweeping Protocols for Detection of Smart Evaders</i>
Christopher WHEAT	<i>Detection and Classification of Unmanned Aerial Vehicles using Commercial Off-The-Shelf Radar Detectors</i>
Qi ZHANG	<i>Towards Lifelong Social Robot Navigation in Dynamic Environments</i>
Brian ANGULO	<i>Evaluation of Safety Constraints in Autonomous Navigation with Deep Reinforcement Learning</i>
Sarfraz AHMED	<i>Investigation of Action Recognition for Improving Pedestrian Intent Prediction</i>
Gjosse ZIJLSTRA	<i>Toward Semi-Autonomous Terrestrial Robots for Atmospheric Electricity Measurement</i>
Zhiyuan YANG	<i>Evaluation of SLAM algorithms for Search and Rescue applications</i>
Mal FAZLIU	<i>Automating Robotic Gas Distribution Mapping in Unknown and GPS-denied Environments</i>
Elif DEGIRMENCI	<i>Developing an Integrated Runtime Verification for Safety and Security of Industrial Robot Inspection System</i>



WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 1: WEDNESDAY, 13 SEPTEMBER 2023

POSTER SESSION 2

LECTURE THEATRE 2 (LT2)

PRESENTER	POSTER
Elijah ALABI	<i>Evaluation Of OSMC Open Source Motor Driver for Reproducible Robotics Research</i>
Lupo MANES	<i>Cable-loop Gripper Add-on for Multimodal Grasping of Lab Supplies</i>
Dexter SHEPHERD	<i>Low-resolution Sensing for Sim-to-real Complex Terrain Robots</i>
Kshitij GAIKWAD	<i>Open Source Hardware Robotics Interfacing Board</i>
Adam SPIERS	<i>Naturalistic Robot Arm Trajectory Generation via Representation Learning</i>
Ciaran DOWDS	<i>Object Feature Reconstruction via Robotic In-Hand-Manipulation and Haptic Proprioception</i>
Ian HOWARD	<i>Design and kinematic analysis of a 3D-printed 3DOF robotic manipulandum</i>
Shibao YANG	<i>Reinforcement Learning-based Adaptive Probabilistic Movement Primitives in Hybrid Scenarios (Extended Abstract)</i>
Laurence ROBERTS-ELLIOTT	<i>Towards an Abstract Lightweight Multi-robot ROS Simulator for Rapid Experimentation</i>
Joshua W. G. GILMOUR	<i>Towards Heterogeneous Modular Robotic Systems for Industrial Applications</i>
James KELLETT	<i>Angled Cantilever Construction by Force-Aware Robotic Swarms</i>



WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

OTHER CONFERENCE ACTIVITIES

13 September

18:30
21:00

Reception & TAROS'23 Dinner
Robinson College

14 September

16:30
17:00

QMUL UK PhD Awards
Department of Engineering

14 September

17:00
17:30

TAROS'23 Awards
Department of Engineering

14 September

17:30
19:00

WOMEN in ROBOTICS
Department of Engineering

14 September

19:30
21:00

ACADEMIC & INDUSTRY NETWORKING
Corpus Christi

15 September

15:00
17:00

FAREWELL RECEPTION
Department of Engineering

08:30 – 09:00

Registration (Day 2)

Courtyard Marquee & LT4/Department of Engineering

DAY 2 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:45

Amanda Prorok

University of Cambridge

09:45 – 10:45

Short Talks: Session 1

Chair:

10:45 – 11:15

Coffee Break & Poster Session

Courtyard Marquee/ LT1 & 2

11:15 – 12:15

Short Talks: Session 2

Chair:

12:15 – 14:00

LUNCH & Poster Session

Courtyard Marquee/ LT1 & 2
/Agriforwards CDT Steering Committee Meeting/

14:00 – 14:45

Gert Kootstra

Wageningen University
Chair: Prof Marc Hanheide

14:45 – 15:45

Industry/Government/UK-RAS Forum

Chair: Manuel Giuliani

15:45 – 16:30

Coffee Break & Poster Session

Courtyard Marquee & LT4/ LT1 & 2

16:30 – 17:00

QMUL UK PhD Awards

Chair: Lorenzo Jamone

17:00 – 17:30

TAROS'23 Awards

Chair: Perla Maiolino

17:30 – 19:00

WOMEN in Robotics

Chair: Isabelle Ormerod
LT1 & 2

19:30 – 21:00

Academic & Industry Networking Event (Corpus Christi)
Cambridge Pub Tour (Student activity)

Dr Amanda Prorok

University of Cambridge



Dr Gert Kootstra

Wageningen University





WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

08:30 – 09:00 **Registration**
Courtyard Marquee & LT4 /Department of Engineering

DAY 2 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:45 **Keynote 3: Amanda Prorok**
University of Cambridge

09:45 – 10:45
**SHORT TALKS:
MULTI-ROBOT**
Chair:

10:45 – 11:15 **Coffee Break & Poster Session**
Courtyard Marquee/ LT1 & 2

11:15– 12:15
**SHORT TALKS:
APPLICATIONS**
Chair:

12:15 – 14:00 **LUNCH & Poster Session**
Courtyard Marquee & LT 4 / LT1 & 2
/Agriforwards CDT Steering Committee Meeting/

14:00 – 14:45 **Keynote 4: Gert Kootstra**
Wageningen University
Chair: Prof Marc Hanheide

14:45 – 15:45 **Industry/Government/UK-RAS Forum**
Chair: Manuel Giuliani

15:45 – 16:30 **Coffee Break & Poster Session**
Courtyard Marquee/ LT1 & 2

16:30 – 17:00 **QMUL UK PhD Awards**
Chair: Lorenzo Jamone

17:00 – 17:30 **TAROS Awards**
Chair: Perla Maiolino

17:30 – 19:00 **Women in Robotics**
Chair: Isabelle Ormerod
LT1 & 2

19:30 – 21:00 **Academics & Industry Networking (Corpus Christi)**
Cambridge Pub Tour (Student activity)

	PRESENTER	PRESENTATION
<p>SHORT TALKS: MULTI – ROBOT</p> <p>CHAIR:</p>	James O'KEEFFE	<i>Hardware Validation of Adaptive Fault Diagnosis in Swarm Robots</i>
	Myles FLANAGAN	<i>Mobile Robots For Collaborative Manipulation Over Uneven Ground Using Decentralised Impedance Control</i>
	Xiaoping ZHANG	<i>Multi-agent Collaborative Target Search Based on Curiosity Intrinsic Motivation</i>
	Fan YE	<i>Simulation of Collective Bernoulli-Ball System for Characterizing Dynamic Self-stability and State Transitions</i>

	PRESENTER	PRESENTATION
<p>SHORT TALKS: APPLICATIONS</p> <p>CHAIR:</p>	Harry ROGERS	<i>An Automated Precision Spraying Evaluation System</i>
	Roopika RAVIKANNA	<i>Smart Parking System Using Heuristic Optimization For Autonomous Transportation Robots In Agriculture</i>
	Jierui SHI	<i>Closed-Loop Robotic Cooking of Soups with Multi-modal Taste Feedback</i>
	Dominic MURPHY	<i>Folding Morphing-wheg Duct-entry Robot for Nuclear Characterisation</i>





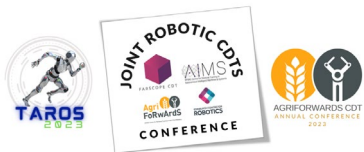
WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 2: THURSDAY, 14 SEPTEMBER 2023

POSTER SESSION 1

LECTURE THEATRE 1 (LT1)

PRESENTER	POSTER
Rachel TRIMBLE	<i>Skid-steer friction calibration protocol for digital twin creation</i>
Barry William MULVEY	<i>Traversing Visually-Similar Physically-Different Obstacles with DeformoBot, a Bio-Inspired Deformable Mobile Robot</i>
Laura ALVAREZ-HIDALGO	<i>Human evaluation of robotic grippers for berry picking</i>
Kedar SUTHAR	<i>Casting vs injection moulding: a comparison study for in-lab low-cost soft robot fabrication</i>
Saloni HAJARE	<i>Suction Cup Detachment Mechanism based on Fluidic Soft Actuators Strain for In-vivo Applications</i>
Kavyan ZOUGHALIAN	<i>Access Control Mechanism Framework for Assistive Robots in Healthcare</i>
Leone COSTI	<i>Comparative study of hand-tracking and traditional control interfaces for remote palpation</i>
Chapa SIRITHUNGE	<i>Estimation of Soft Body Deformation by Using Light</i>
Srikishan VAYAKKATTIL	<i>Plant phenotyping using DLT method: Towards retrieving the delicate features in a dynamic environment</i>
Huijiang WANG	<i>Reduced-Order Modeling of a Soft Anthropomorphic Finger for Piano Keystrokes</i>
Joseph SOGUNRO	<i>Multi-axis Force and Tactile Sensor Sleeves for Micro Catheters & Cannulas</i>
Rafi HOSSAIN	<i>Prototyping Mechanical Design of a Robotic Tail for Human Balance Support</i>
Elijah ALMANZOR	<i>Rapid Development and Performance Evaluation of a Potato Planting Robot</i>



WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 2: THURSDAY, 14 SEPTEMBER 2023

POSTER SESSION 2

LECTURE THEATRE 2 (LT2)

PRESENTER	POSTER
Andrew WEST	<i>Sonification of Ionising Radiation Data for Robot Operators</i>
Burak KIZILKAYA	<i>5G-based Low-Latency Teleoperation: Two-way Timeout Approach</i>
Nasiru ABOKI	<i>Automating a Telepresence Robot for Human Detection, Tracking, and Following</i>
Hyeonggeun YUN	<i>Generative Model-based Simulation of Driver Behavior when Using Control Input Interface for Teleoperated Driving in Unstructured Canyon Terrains</i>
Seth ROBERTS	<i>Human Machine Interface for a Pick-and-Place Task Using Extended Reality Devices</i>
Aaron SMILES	<i>Implementation and Validation of a Stereo Vision System for Robotic Teleoperation Simulator</i>
Emanuele DE PELLEGRIN	<i>Towards Multimodal Sensing and Interaction for Assistive Autonomous Robots</i>
Imene TARAKLI	<i>Personalised Interactive Reinforcement Learning with Multi-Task Pre-training</i>



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DAY 3: FRIDAY, 15 SEPTEMBER 2023

08:00 – 09:00 **Registration (Day 3)**
Courtyard Marquee/Department of Engineering

DAY 3 ACTIVITIES: Dr Constance Tipper Lecture Theatre

09:00 – 09:30 **CDT Session INTRO**
Chairs: Fumiya Iida/Marc Hanheide

09:30 – 10:30 **EDINBURGH Centre for ROBOTICS**
Chair: Marc Hanheide

10:30 – 11:00 **BREAK: Refreshments**
Courtyard Marquee/Department of Engineering

11:00 – 12:00 **FARSCOPE (Bristol)**
Chair: Helen McGloin

12:00 – 12:30 **CDT Panel: Student Training & Career**
Chair:

12:30 – 13:30 **LUNCH & Poster Session**
Courtyard Marquee & LT 4 / LT1 & 2

13:30 – 14:30 **AIMS (Oxford)**
Chair:

14:30 – 15:00 **CDT Panel: Future Collaborations**
Chair:

15:00 – 17:00 **Farewell Reception & Poster Session**
Agriforwards CDT Posters/Robotic Demonstrations
LT1 & 2/OHMC

	PRESENTER	PRESENTATION
EDINBURGH CENTRE FOR ROBOTICS CHAIR: MARC HANHEIDE	Sabrina McCALLUM	
	Houman MEHRAFARIN	
	Meriam MOUJAHID	
	Paul BAISAMY	

	PRESENTER	PRESENTATION
FARSCOPE (BRISTOL) CHAIR:	Helen McGLOIN & Ella MAULE	<i>Sustainability in Robotics workshop</i>
	Isabelle ORMEROD	<i>Women in Robotics</i>

	PRESENTER	PRESENTATION
AIMS (OXFORD) CHAIR:	Yash BHALGAT	
	Benjamin ELLIS	
	Cong LU	

AGRIFORWARDS CDT POSTER SESSION & FAREWELL RECEPTION

Agriforwards CDT Students' posters to be displayed in LT 1& 2 alongside Robotic Demonstrations in the OHMC





WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 3: FRIDAY, 15 SEPTEMBER 2023

POSTER SESSION 1

LECTURE THEATRE 1 (LT1)

PRESENTER	POSTER
Afsaneh KARAMI	
Alex ELIAS	
Amie OWEN	
Andrew PERRETT	
Andrew SIMPSON	
Bethan MONCUR	<i>Deciding to Implement Emerging Technologies: the Use of Digital Technologies in Planning the Implementation of Robotics and Autonomous Systems (RAS) in Food Manufacturing Firms</i>
Callum LENNOX	
Calvin JOHN	
Charalampos MATSANTONIS	<i>Characteristic Multivector Fitting of Two 3D Point Sets</i>
Grey CHURCHILL	
Elijah ALMANZOR	<i>Shape Control of Soft Continuum Robots Using Drawn Images</i>
Emlyn WILLIAMS	
Garry CLAWSON	<i>Designing Food Supply Chain for Nutritional Delivery and Traceability</i>
Grzegorz SOCHACKI	<i>Improving Robotic Taste Performance in Classification Task with Mastication</i>
Hai Hui YAN	<i>Printing Soft Robotic Gripper for Automated Strawberry Harvesting</i>
Harry ROGERS	



WELCOME TO TAROS'23 & JOINT ROBOTICS CDT CONFERENCE

DAY 3: FRIDAY, 15 SEPTEMBER 2023

POSTER SESSION 2

LECTURE THEATRE 2 (LT2)

PRESENTER	POSTER
Jack BRADLEY	
Jack FOSTER	<i>Uncertainty-Guided Multi-Agent Continual Learning for Food Supply-Chain Knowledge Graph Completion</i>
James BENNETT	
James HESELDEN	
Karoline HEIWOLT	<i>Statistical shape representations for temporal registration of plant components in 3D</i>
Kyle FOGARTY	<i>Neutral Geometry Processing for 3D Natural Structure Modelling</i>
Mazvydas GUDELIS	
Paul-David ZUERCHER	<i>Optimising Immersive Assistance Systems for Managing Automated Manufacturing Operations with Limited Resources</i>
Prabuddhi WARIYAPPERUMA	
Rachel TRIMBLE	<i>Integrating Epidemiological Modelling with Reinforcement Learning for Effective Controls of Invasive Plant Disease</i>
Roopika RAVIKANNA	
Vijja WICHITWECHKARN	<i>Making MACARONS</i>
William ROHDE	<i>Precision Agriculture: Controlling Crop Growth</i>
Willow MANDIL	<i>Combining Visual and Tactile Sensation to Enhance Physical Robot Interactions</i>
Xumin GAO	
Yi ZHANG	